

Figure 1. Signal conditioning is an important component of a PC-based DAQ system.

### Introduction

PC-based data acquisition (DAQ) systems and plug-in devices are used in a very wide range of applications in the laboratory, in the field, and on the manufacturing plant floor. Typically, DAQ plug-in devices are general-purpose instruments that are well suited for measuring voltage signals.

However, most real-world sensors and transducers generate signals that you must condition before a DAQ device can reliably and accurately acquire the signal. This front-end processing, referred to as signal conditioning, includes functions such as signal amplification, filtering, electrical isolation, and multiplexing. Therefore, most PC-based DAQ systems include some form of signal conditioning in addition to the plug-in DAQ device and personal computer, as shown in Figure 1.

Front-end switching systems also increase the functionality of your measurement and automation system. General-purpose switching delivers digital control of the presence or absence of a signal in your system, such as power to a motor. Multiplexer/matrix relay configurations control source and signal routing for your system, or act as a multiplexing front end for devices such as digital multimeters (DMMs).

### Transducer Conditioning

Transducers are devices that convert physical phenomena, such as temperature, strain, pressure, or light, into electrical properties, such as voltage or resistance. Transducer characteristics define many of the signal conditioning requirements of a DAQ system.

### Thermocouples

The most popular transducer for measuring temperature is the thermocouple. Although the thermocouple is inexpensive, rugged, and can operate over a very wide range of temperatures, the thermocouple has some unique signal conditioning requirements.

A thermocouple operates on the principle that the junction of two dissimilar metals generates a voltage that varies with temperature. However, connecting the thermocouple wire to the wire that connects it to the measurement device creates an additional thermoelectric junction, referred to as the cold junction. The actual measured voltage, V<sub>MEAS</sub>, therefore includes both the thermocouple voltage and the cold-junction voltages (V<sub>CJ</sub>) (see Figure 2). The method of compensating for these unwanted cold-junction voltages is called cold-junction compensation.

Most of the NI signal conditioning products compensate for coldjunctions by using an additional sensor, such as thermistor or IC sensor,

placed on the signal connector or terminal block to measure the ambient temperature at the cold junction directly. Software can then compute the appropriate compensation for the unwanted thermoelectric voltages.

Sensitivity and noise are also important measurement issues with thermocouples. Thermocouple outputs are very low in level and change only 7 to 50 µV for every 1 °C change in temperature, making the signals very susceptible to the effects of electrical noise. Therefore, thermocouple conditioners include lowpass noise filters for suppressing 50 and 60 Hz noise and high-gain instrumentation amplifiers to boost the level of the signal.



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Amplifying the thermocouple signal also increases the resolution, or sensitivity, of the measurement. For example, a typical DAQ device with an ADC input range of  $\pm 10$  V and an onboard gain of 50 has a resolution of 98  $\mu$ V. This corresponds to about 2 °C for a type J or K thermocouple. However, by adding a signal conditioner with an additional gain of 100 to the system, the measurement resolution increases to 1  $\mu$ V, which corresponds to a fraction of a degree Celsius.

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Figure 2. The connection of thermocouple wires to a measurement system creates an additional thermoelectric junction, called the cold junction, which must be compensated for with signal conditioning.

#### RTDs

Another popular temperature-sensing device is the resistancetemperature detector (RTD), a device whose resistance increases with temperature. The most popular type of RTD is made of platinum and has a nominal resistance of 100  $\Omega$  at 0 °C. Because an RTD is a resistive device, you must pass a current through the RTD to produce a voltage that a DAQ device can measure. With relatively low resistance (100  $\Omega$ ) that changes only slightly with temperature (less than 0.4  $\Omega$ /°C), RTDs require signal conditioners with high-precision excitation current sources, high-gain amplifiers, and provisions for four-wire and threewire measurements that minimize lead error effects.

For example, a two-wire RTD measurement, shown in Figure 3a,



includes voltage drop errors caused by the excitation current passing through lead resistance, R<sub>I</sub>. These errors, which can be significant, are removed by using a four-wire RTD measurement, shown in Figure 3b. The four-wire configuration uses a second pair of wires to carry the excitation current to the RTD. Therefore. only negligible current flows through the sensing wires, so the lead resistance error is very small.

Figure 3. Errors cause by lead wire resistance,  $R_{L'}$  are minimized by using a four-wire measurement for RTDs.

### **Strain Gauges**

The strain gauge is a device commonly used in mechanical testing and measurement. The most common gauge, the bonded-resistance strain gauge, consists of a grid of very fine foil or wire whose electrical resistance varies linearly with the strain applied to the device. When using a strain gauge, you bond the strain gauge to the device under test, apply force, and measure the strain by detecting changes in resistance. Strain gauges are also used in sensors that detect force or other derived parameters, such as acceleration, pressure, and vibration.

Because strain measurement requires detecting very small changes in resistance, the Wheatstone bridge circuit is used predominantly. The Wheatstone bridge circuit consists of four resistive elements with a voltage excitation supply applied to the ends of the bridge. Strain gauges can occupy one, two, or four arms of the bridge, with any remaining positions filled with fixed resistors. Figure 4 shows a configuration with a half-bridge strain gauge consisting of two strain elements,  $R_{G1}$  and  $R_{G2}$ , combined with two fixed resistors,  $R_1$  and  $R_2$ .

With a voltage  $V_{EXC}$  powering the bridge, the measurement system measures the voltage  $V_{MEAS}$  across the bridge. In the unstrained state, when the ratio of  $R_{G1}$  to  $R_{G2}$  equals the ratio of  $R_1$  to  $R_2$ , the measured voltage  $V_{MEAS}$  is 0 V. This condition is referred to as a balanced bridge. As strain is applied to the gauges, their resistance values change, causing a change in the voltage at  $V_{MEAS}$ . Strain-gauge conditioning products have voltage excitation sources, gain amplifiers, and provisions for bridge-completion resistors (see Figure 5), which should be very precise and stable. Because strain-gauge bridges are rarely balanced perfectly, some signal conditioners also use offset nulling, a process in which you adjust the resistance ratio of the unstrained bridge to balance the bridge and remove any initial DC offset voltage. Alternatively, you can measure this initial offset voltage and use this measurement in your conversion routines to compensate for the unbalanced initial condition.



Figure 4. Strain gauges are measured in a Wheatstone bridge configuration.

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Figure 5. Connection of Half-Bridge Strain Gauge Circuit.

### LVDTs

A linear voltage differential transformer (LVDT) is a device commonly used to measure linear displacement. All LVDTs consist of a stationary coil assembly and a movable core (see Figure 6). The coil assembly houses a primary and two secondary windings. The core is a steel rod of high magnetic permeability, and is smaller in diameter than the internal bore of the coil assembly, so you can mount the rod and assure that no contact is made with the coil assembly. Thus the rod can move back and forth without friction or wear.

When an AC excitation voltage is applied to the primary winding, a voltage is induced in each secondary winding through the magnetic core. The position of the core determines how strongly the excitation signal couples to each secondary winding. When the core is in the center, the voltage of each secondary coil is equal and 180 degrees out of phase, resulting in no signal. As the core travels to the left of center, the primary coil is more tightly coupled to the left secondary coil, creating an output signal in phase with the excitation signal. As the core travels to the right of center, the primary coil is more tightly coupled to the right secondary coil, creating an output signal 180 degrees out of phase with the excitation voltage.



Figure 6. Cross-section of an LVDT





#### **Accelerometers**

An accelerometer is a device commonly used to measure acceleration and vibration (see figure 7). It consists of a known mass attached to a piezoelectric element. As the accelerometer moves, the mass applies force to the crystal, generating a charge. By reading this charge, you can determine acceleration. Accelerometers are directional, measuring acceleration along only one axis. To monitor acceleration in three dimensions, choose a multiaxis accelerometer.



Accelerometers are available in two types, passive and active. Passive accelerometers send out the charge generated by the piezoelectric element. Because the signal is very small, passive accelerometers require a charge amplifier to boost the signal and serve as a very high impedance buffer for your DAQ device. Active accelerometers include internal circuitry to convert the accelerometer charge into a voltage signal, but require a constant current source to drive the circuitry.



Figure 8. Process current signals, usually 0 to 20 mA or 4 to 20 mA, are converted to voltage signals using precision resistors.

### **Current Signals**

Many devices or transmitters used in process control and monitoring applications generate a current signal, usually 0 to 20 mA or 4 to 20 mA. Current signals are used because they are more immune to errors caused by radiated noise and voltage drops on long wire runs. Signal conditioners convert current signals to a voltage signal by passing the input current signal through a precision resistor, as shown in Figure 8. The resulting voltage,  $V_{MEAS} = I_S R$ , can then be further conditioned and digitized.

### General Signal Conditioning Functions

In addition to handling specific transducers, signal conditioners perform a variety of general-purpose conditioning functions to improve the quality, flexibility and reliability of your measurement system.

### **Signal Amplification**

Because real-world signals are often very small in magnitude, signal conditioning can improve the accuracy of your data. Amplifiers boost the level of the input signal to better match the range of the analog-to-digital converter (ADC), thus increasing the resolution and sensitivity of the measurement. While many DAQ devices include onboard amplifiers for this reason, many transducers, such as thermocouples, require additional amplification.

In addition, using external signal conditioners located closer to the signal source, or transducer, improves the signal-to-noise ratio of the measurement by boosting the signal level before it is affected by environmental noise.

### Filtering

Additionally, signal conditioners can include filters to reject unwanted noise within a certain frequency range. Almost all DAQ applications are subject to some degree of 50 or 60 Hz noise picked up from power lines or machinery. Therefore, most conditioners include lowpass filters designed specifically to provide maximum rejection of 50 or 60 Hz noise. For example, the SCXI-1125 module includes a lowpass filter



Figure 9. Isolation removes common-mode voltage errors, typically caused by differences in ground potentials.

with a cutoff bandwidth of 4 Hz so that rejection of 50 or 60 Hz noise is maximized (90 dB).

Another common use of filters is to prevent signal aliasing – a phenomenon that arises when a signal is undersampled (sampled too slowly). The Nyquist theorem states that when you sample an analog signal, any signal components at frequencies greater than one-half the sampling frequency appears in the sampled data as a lower frequency signal. You can avoid this signal distortion only by removing any signal components above one-half the sampling frequency with lowpass filters before the signal is sampled. Some signal conditioners, such as the SCXI-1141, that are used for vibration monitoring and other dynamic signal measurements include special antialiasing filters that feature programmable bandwidth (variable according to the sampling rate) and very sharp filter rolloff.

#### Isolation

Improper grounding of the system is one of the most common causes of measurement problems, noise, and damaged DAQ devices. Isolation removes common-mode voltage errors, typically caused by differences in ground potentials (see Figure 9). See page 463 for more information on isolation.

### Multiplexing

Most plug-in DAQ devices include eight differential or 16 single-ended analog input channels, with some options as high as 64 single-ended channels. External signal conditioners with multiplexing can economically expand the capacity of the DAQ device to handle large numbers of channels. For example, SCXI modules multiplex conditioned signals onto the SCXIbus in the backplane of the Tutorial

chassis for connection to a digitizing DAQ device (See Figure 10). In this way, you can condition and multiplex up to 3,072 analog input channels and digitize them with a single DAQ device.

#### **Matrix Switching**

Matrix switching offers greater flexibility by programmatically routing signals and sources to and from different test units. A matrix device is described in terms of columns and rows. Test I/O lines are typically connected to the columns and test equipment is typically connected to the rows. You can programmatically route any row or rows to any column or columns by closing the corresponding relays. You can route a single row to several columns or a single column to a group of rows. With such a configuration you can drive or sense any I/O signal connected to the system without reconnecting any wires.

### Digital Signal Conditioning/General-Purpose Switching

Digital or discrete signals also have conditioning needs. Most commonly, digital I/O devices either drive or sense TTL and CMOS-compatible 5 V logic levels. Relays of some sort are required to interface with real-world switching levels. General-purpose switching means controlling the state of an electromechanical or solid-state relay with a digital output signal from a DAQ device. The relay, which is equipped to handle higher power than the DAQ device, also isolates these power signals from your computer. With general-purpose switching, you can control external motors, valves, solenoids, and lamps.



Figure 10. Multiplexing signal conditioners, such as SCXI, combine conditioning and multiplexing to handle very large numbers of channels in an efficient and economical manner.